

Adapting Modeling Instruction to DIY Arduino (Microcontroller) Lab Equipment Development

A longer version of this talk is online at <http://youtu.be/7uYC-EuIFJA>

Also, a short paper lives at <http://arxiv.org/abs/1407.7613>

2014 July 29, 9:50-10am

Tate Lab, 133

AAPT, Summer 2014

Nathan Moore, Winona State University

Andrew Haugen, Winona State University

Thanks to: Scot Stroh, Tia Troy, Megan Reiner,
Birat Sapkota, WSU Physics 221 classes in Spring 2011 and 2013,
and Paul Lulai

College Physics 1, What's the rotational speed of the Big Dipper?

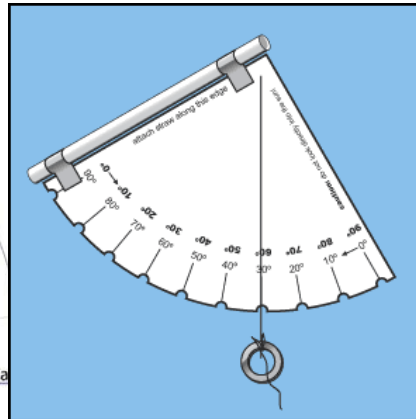
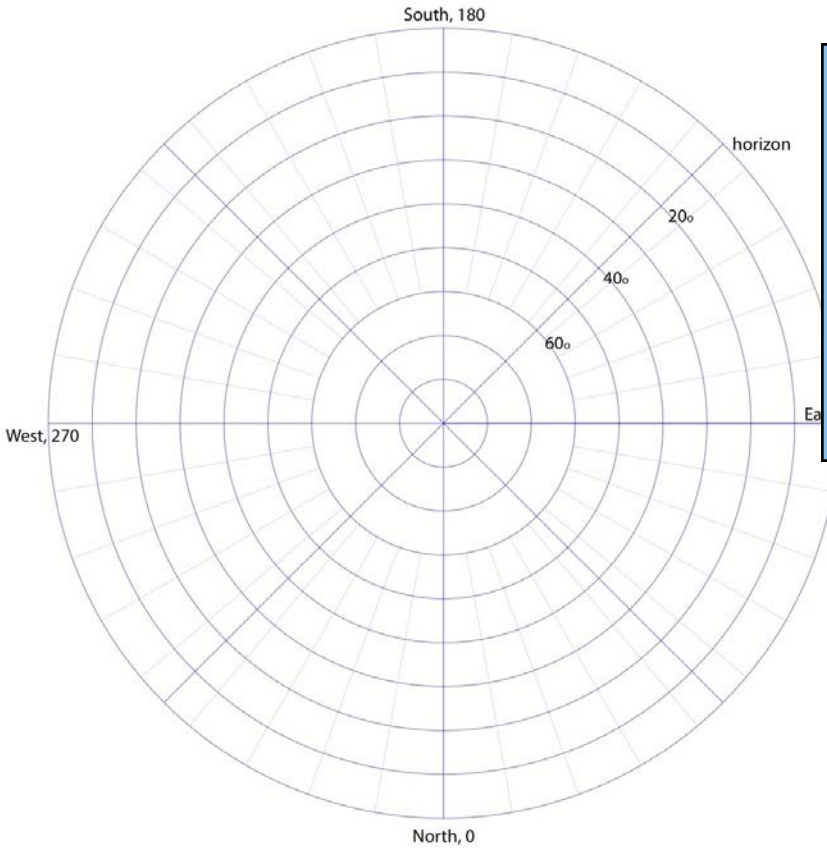
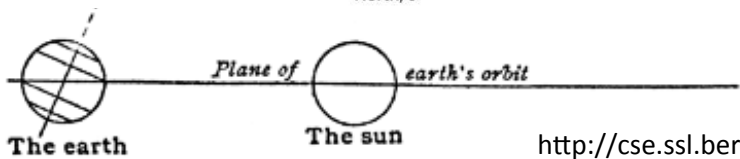
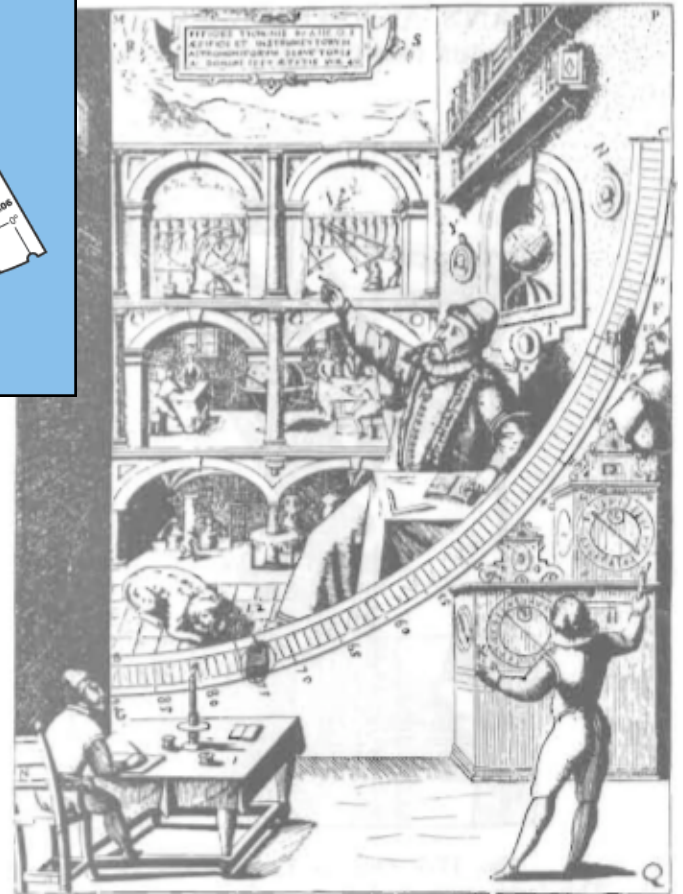


FIG. 17-5. TYCHO'S MURAL QUADRANT
The huge brass arc was firmly fixed in a western wall, with its center at an open window in a southern wall. The empty wall above the arc was decorated by a huge painting showing: Tycho observing; students calculating; Tycho's globe, books, dog; and some of Uraniborg's main instruments. An observer sighted the star (or Sun) by pinholes at F and a marker in the window. The brass arc (radius over 6 ft.) could be read to $\frac{1}{500}$ degree. This sketch, from Tycho's own book, shows an observer at F, a recorder, and a timekeeper with several clocks. Good clocks had not been invented, but these were the best Tycho could make.

QVADRANS MVRALIS SIVE TICHONICUS



What would it be like if every student had their own motion detector in their dorm room? What would they do?



See the editor of Make on Colbert,

<http://www.colbertnation.com/the-colbert-report-videos/311944/june-08-2010/mark-frauenfelder>

“Makerspace in the Classroom”

<http://makezine.com/2014/01/10/makerspace-in-the-classroom/>

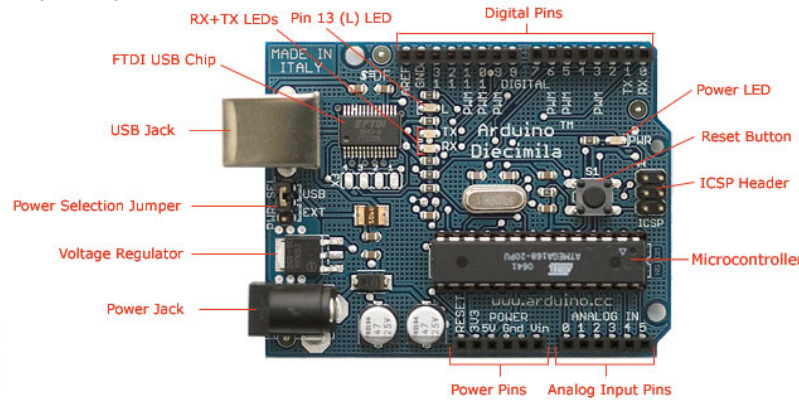
Hey, isn't this talk about Arduinos?

- ATMega328 microcontroller, 8bit, 16MHz, 2k RAM
- 14 Digital I/O pins
- 6 Analog inputs (10+ bit ADC)
- Pre-built sensor arrays, "shields"
- "open hardware"
- Open-source programmer (IDE)
- Program in "C-tran"

3-Axis Accelerometer
\$20



Ultrasonic
Distance \$30



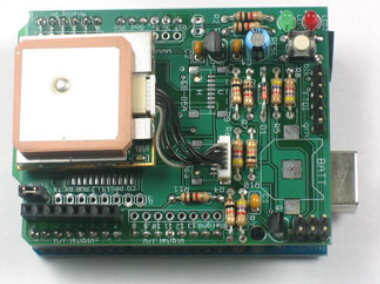
Photograph by SparkFun Electronics. Used under the Creative Commons Attribution Share

We can all be
Eratosthenes.

IR Distance



GPS Shield + Antenna (\$50)



Gas (ethanol, CO, etc)

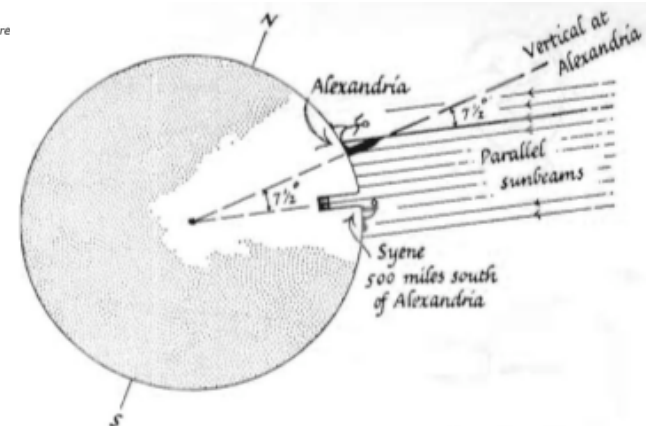
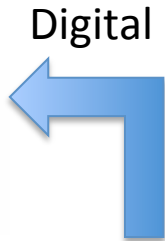
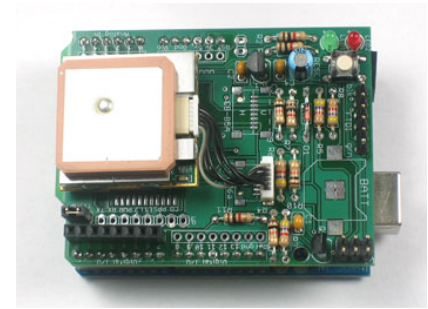
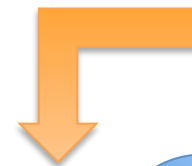


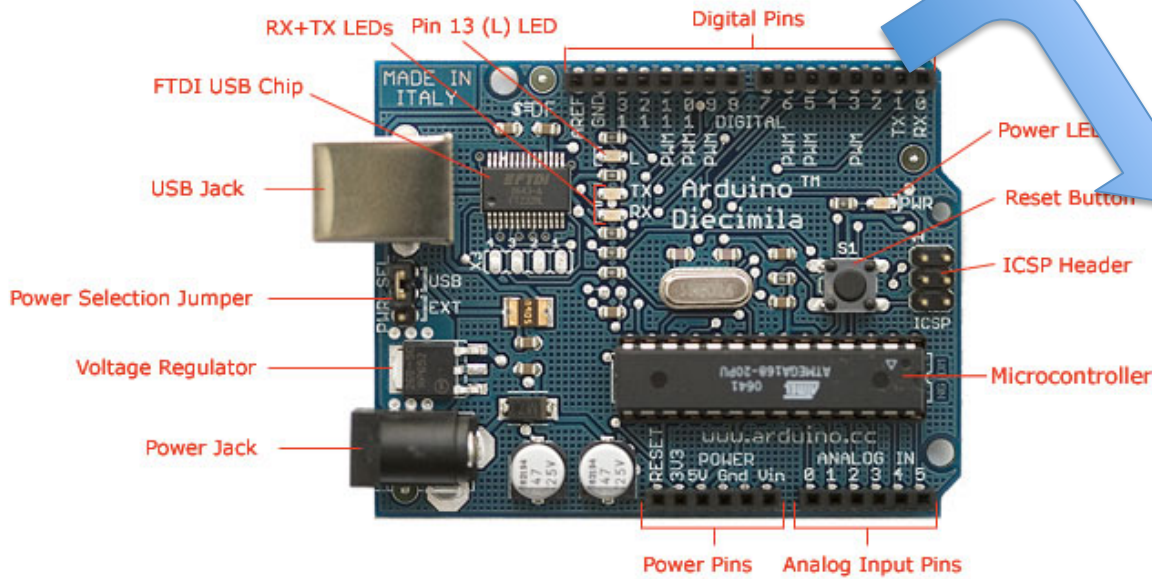
FIG. 14-14. HOW ERATOSTHENES ESTIMATED THE SIZE OF THE EARTH



Digital
00011010100



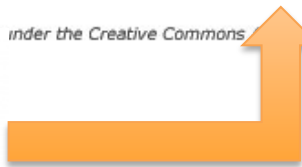
GPS



Analog (PWM) out



Photograph by S... under the Creative Commons Attribution Share-Alike 3.0 license.



Analog, 0-5v

Data/Control Flow

Implementation at WSU

Physics 221, Calculus-based Intro mechanics

- Engineering, Chemistry, Math, Physics majors
- Students buy a “labkit” consisting of Arduino+sensors
- Standard lecture
- Lab consists of making DAQ equipment and then using it (2 week cycle)
- Trial 1, Programming via Arduino code editor (2011)
- Trial 2, Programming via Labview (2013)

Outcomes

- One student gets an internship at SpaceX
- Some senior engineering design projects include Arduino programming
- Some students take the Labview certification exam (beginner)
- One student solves numerical integration (MS Excel) program w/ Arduino
- MPEX results are unremarkable <http://www.physics.umd.edu/perg/expects/>
- Student attitudes are mixed
- Students love soldering

How do you program a dishwasher?

(That's what the micro inside an arduino is used for...)

Assembly

“Arduino” language
(subset of C/C++)

Avoid fancy function calls,
Floating point math,
Pointers, C++ etc

2000 bytes of memory means:

500 long ints

or

1000 ints (0-64k)

or

500 floats

or

2000 characters

```
Blink | Arduino 1.0.5
Blink
/*
  Blink
  Turns on an LED on for one second, then off for one second, repeatedly.

  This example code is in the public domain.
  */

// Pin 13 has an LED connected on most Arduino boards.
// give it a name:
int led = 13;

// the setup routine runs once when you press reset:
void setup() {
  // initialize the digital pin as an output:
  pinMode(led, OUTPUT);
}

// the loop routine runs over and over again forever:
void loop() {
  digitalWrite(led, HIGH); // turn the LED on (HIGH is the voltage level)
  delay(1000);             // wait for a second
  digitalWrite(led, LOW);  // turn the LED off by making the voltage LOW
  delay(1000);             // wait for a second
}
```

Setup() {
Done 1x

Loop() {
Forever...

1 Arduino Uno on /dev/tty.usbmodem1411

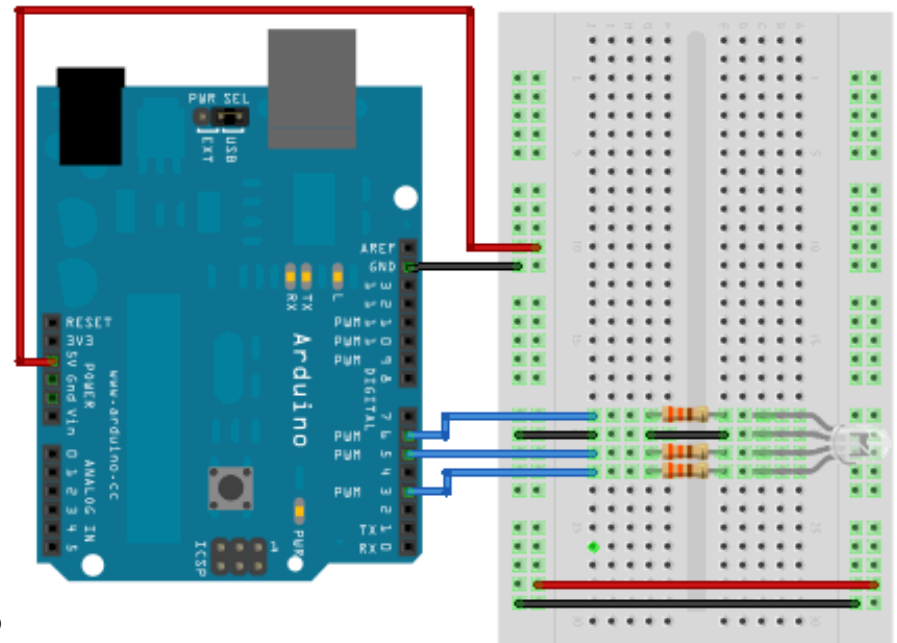
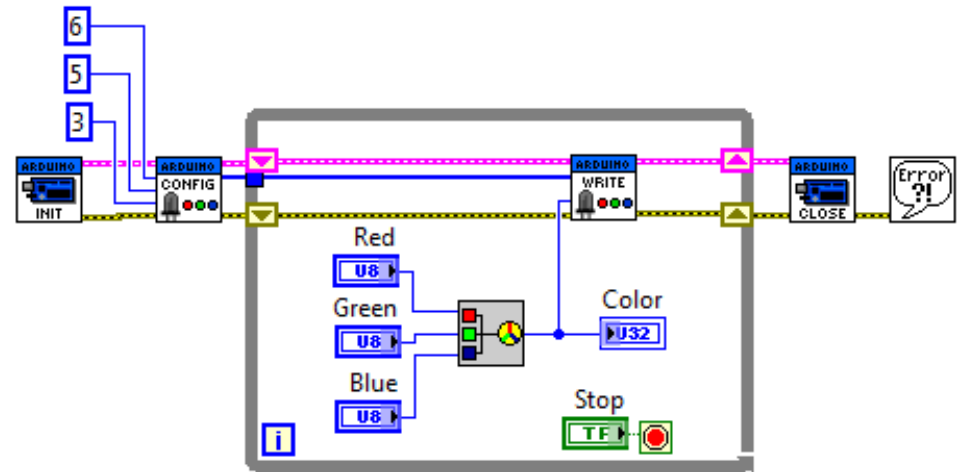
Or, how do you program a Steelmill?

National Instruments
“Labview”
(Programming “by
cartoon”)

Widely used in
Engineering Test Industry,
DSP

Arduino+Student Edition
for ~\$50

Similar to Lego NXT
programming



How do you teach a (physics) student to program (in physics)?

What is an algorithm?

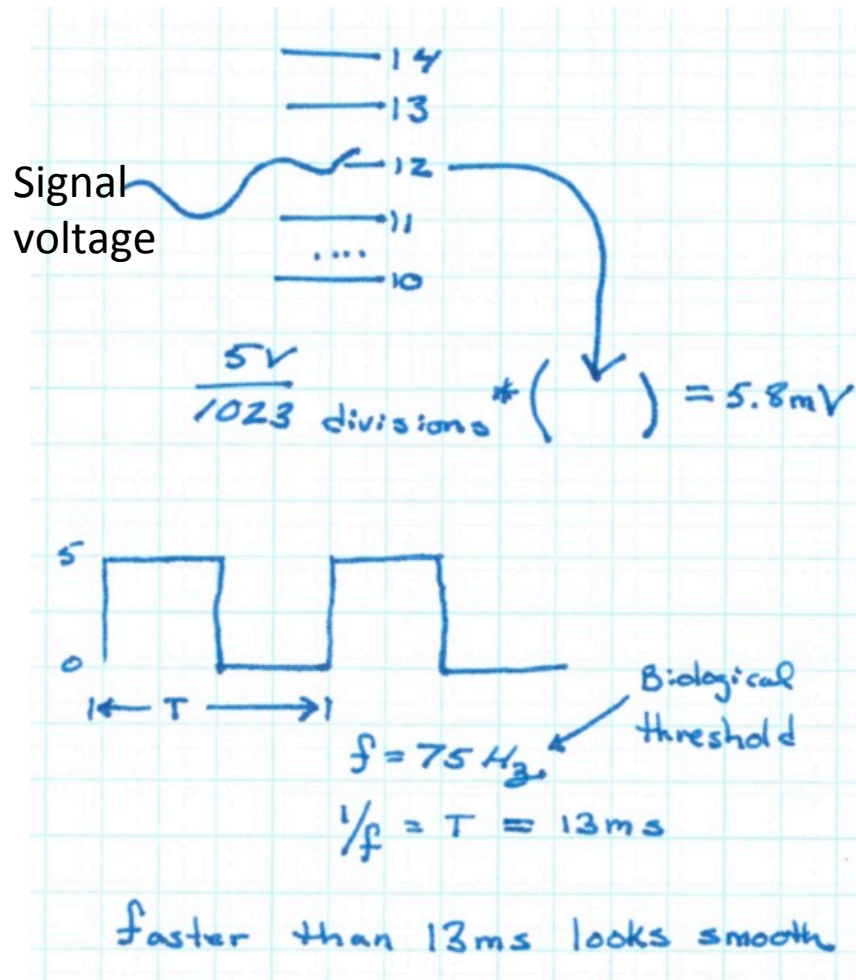
See “Math from 3 to 7,”
A. Zvonkin, MRSI/AMS, or



```
Blink | Ar  
✓ → 📄 ⬆ ⬇  
Blink  
/*  
Blink  
Turns on an LED on for one second, the  
  
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  delay(1000); // wait for  
  digitalWrite(led, LOW); // turn the  
  delay(1000); // wait for  
}
```

How do you teach a (physics) student to interface a microcontroller (in physics)?

Analog to Digital Conversion (ADC)



Pulse Width Modulation (PWM)

```
ReadAnalogVoltage | Arduino 1.0.5

ReadAnalogVoltage

/*
  ReadAnalogVoltage
  Reads an analog input on pin 0, converts it to voltage, and prints
  the result to the serial port.
  Attach the center pin of a potentiometer to pin A0, and the outside
  pins to ground and +5V.

  This example code is in the public domain.
  */

// the setup routine runs once when you press reset:
void setup() {
  // initialize serial communication at 9600 bits per second:
  Serial.begin(9600);
}

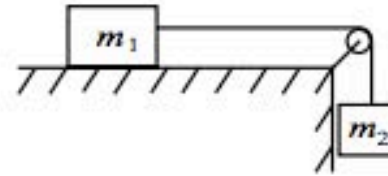
// the loop routine runs over and over again forever:
void loop() {
  // read the input on analog pin 0:
  int sensorValue = analogRead(A0);
  // Convert the analog reading (which goes from 0 - 1023) to a
  float voltage = sensorValue * (5.0 / 1023.0);
  // print out the value you read:
  Serial.println(voltage);
}
```

How does Modeling come into play?

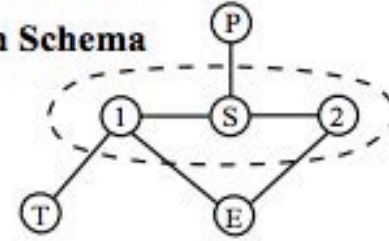
- 3wk workshops, ASU
- Physics (Physical Science, Mechanics, E&M), Chemistry, Biology
- Incredibly high FCI gains, PISA scores, student maturity
- Students are “prepared for college”
- True Vygotskian social construction

Representations of structure in a model for the modified Atwood machine

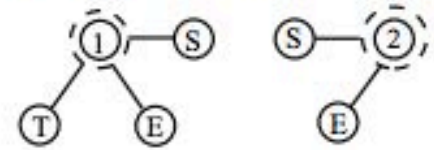
Situation Map



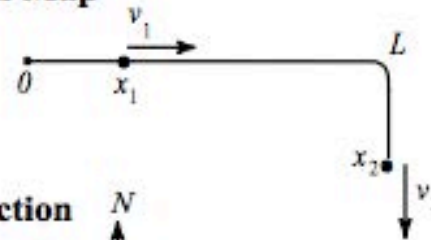
System Schema



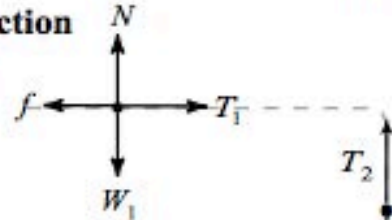
Subsystem Schema



Motion Map



Interaction Map



**Temporal Structure
(Equations of Motion)**

For single particle subsystems:

$$\begin{aligned} T_1 - \mu N &= m_1 a_1 \\ m_2 g - T_2 &= m_2 a_2 \\ N &= m_1 g \end{aligned}$$

For entire 2 particle system:

$$m_2 g - \mu m_1 g = (m_1 + m_2) a_1$$

Geometric Structure

$$\begin{aligned} x_2 &= x_1 + L \\ \Rightarrow v_2 &= v_1 \\ \Rightarrow a_2 &= a_1 \end{aligned}$$

Interaction Laws

$$\begin{aligned} \text{Internal: } T_1 &= T_2 \\ \text{External: } f &= \mu N \\ W_1 &= m_1 g \\ W_2 &= m_2 g \end{aligned}$$

Model Development



Model Deployment

For more, see:

<http://modelinginstruction.org/>

<http://youtu.be/3GkY-ZXnx4w>

http://modeling.asu.edu/modeling/mod_cycle.html

<http://modeling.asu.edu/R&E/ModelingMeth-jul98.pdf>

Modeling “Model” for DIY Sensors

Model Development



1. Context-rich Concrete preparation
2. Sensor Data Collection
3. Mathematical Model-Building
4. Algorithmic Model-Building

Model Deployment

5. (Engineering) Applications

Model Development

1. Context-rich Concrete preparation
2. Sensor Data Collection
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Model Deployment

5. (Engineering) Applications

Context-Rich Concrete Preparation

Over the summer you have a job working for a medical technology start-up in Rochester, MN. The company is working on a high-precision infra-red incubator to be used in the maternity ward of hospitals for newborn babies, and you're excited to be able to help on the project.

In your first week, your boss asks you to familiarize yourself with temperature measuring equipment (obviously, the incubator can't allow the baby to be chilled or overheat, and the control circuitry has to be designed accordingly). The specific device she wants you to work with is an LM34 temperature probe, which is made by National Semiconductor (among others). A data sheet for the LM34 is available (attached). Please read through the datasheet.

The specific wiring diagram for the LM34 is given in figure ???. From reading through the datasheet, you should be able to determine appropriate values for V_S and the numerical conversion from V_{OUT} to a sensor temperature, measured in degrees Fahrenheit.

You should be able to supply V_S and GND from your Arduino, and V_{OUT} can be read either with a voltmeter or one of the analog-to-digital (A2D) pins on your Arduino.

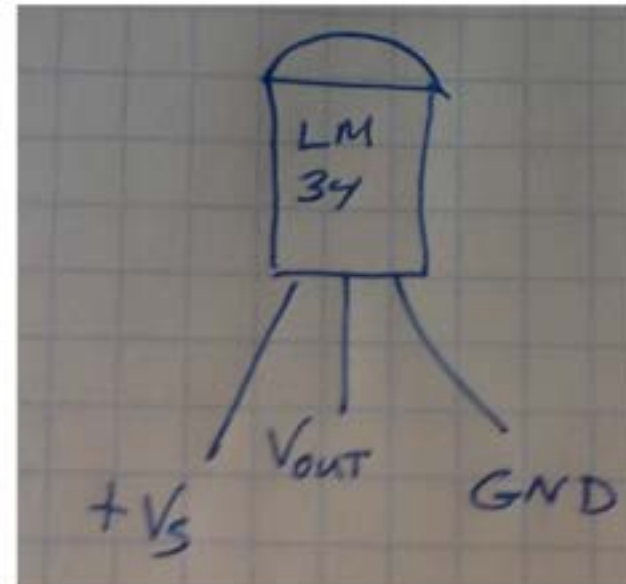
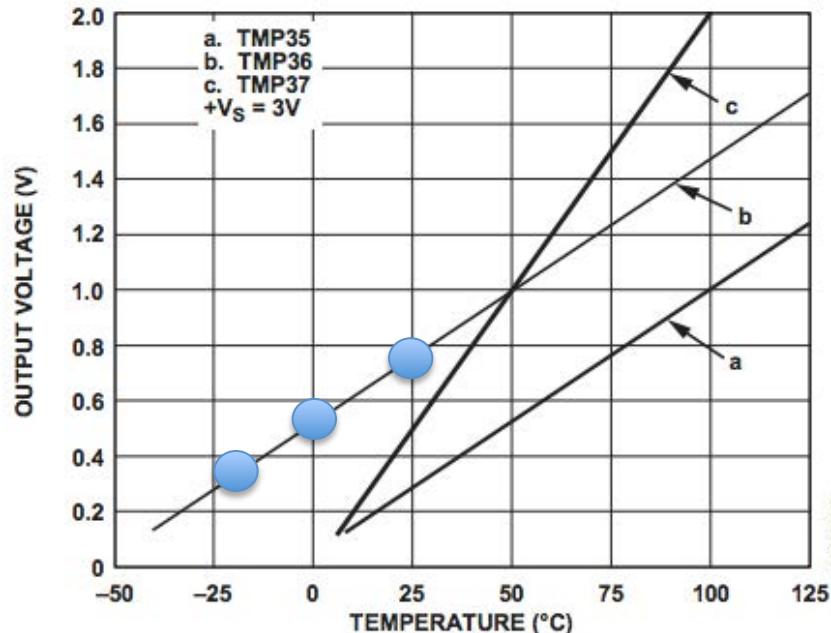


Figure 2: Wiring pin-out for an LM-34 Temperature probe.

Sensor Data Collection/Calibration



Model Development

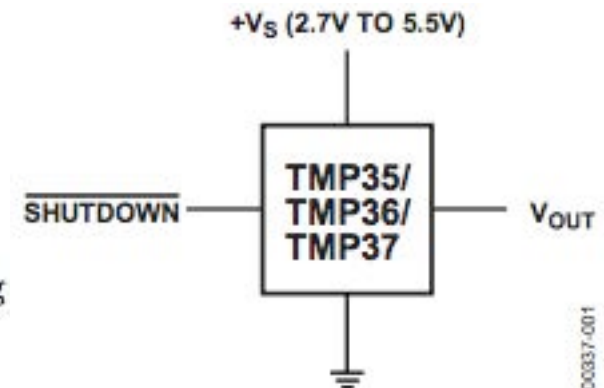
1. Context-rich Concrete preparation
2. Sensor Data Collection
3. Mathematical Model-Building
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Model Deployment

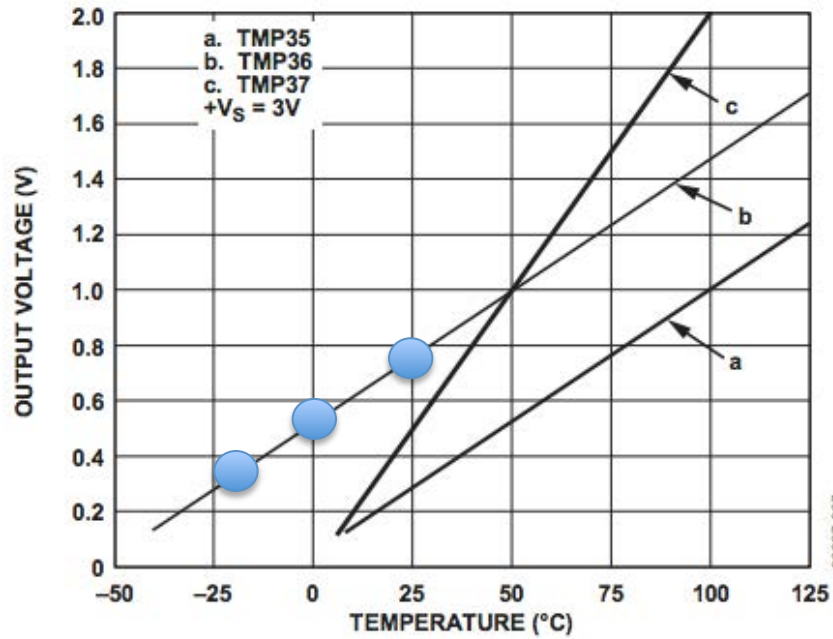
5. (Engineering) Applications

After wiring up your LM34 sensor, please take data (using a glass thermometer as a control), which characterizes the behavior of the sensor. Please make sure your data allows you to answer the following questions:

1. What pin, and in what way do you measure sensor voltage?
2. How do you convert the sensor voltage into a sensor temperature?
3. How long does it take the sensor to equilibrate with its surroundings?
4. What's the min/max surface temperature of your body? (be modest!)
5. How does the value read from the LM34 compare (in accuracy) to a reading glass thermometer?
6. Is the calibration formula given in the datasheet reliable?
7. To what accuracy does the sensor allow you to measure temperature?



Mathematical Model-Building



Model Development

1. Context-rich Concrete preparation
2. Sensor Data Collection
3. Mathematical Model-Building
4. Algorithmic Model-Building

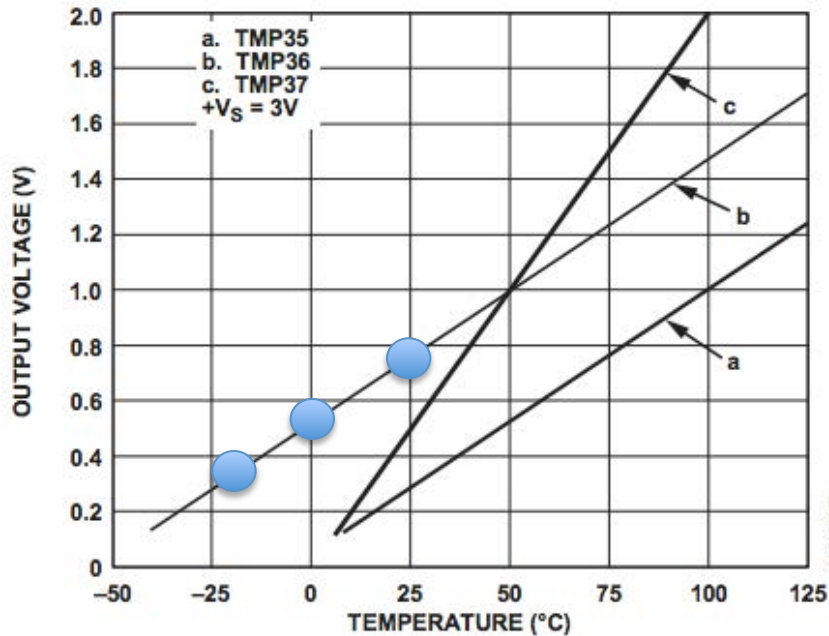
Model Deployment

5. (Engineering) Applications

With data collected, please build a mathematical model which allows you to predict sensor temperature based on the voltage the sensor reports. To create this model, you should first produce a graph of sensor temperature as a function of output voltage. A mathematical model should be accessible from the data you plot.

$$\text{Voltage} = a (\text{Temperature}) + b$$

Algorithmic Model-Building



Model Development

1. Context-rich Concrete preparation
2. Sensor Data Collection
3. Mathematical Model-Building
4. Algorithmic Model-Building

Model Deployment

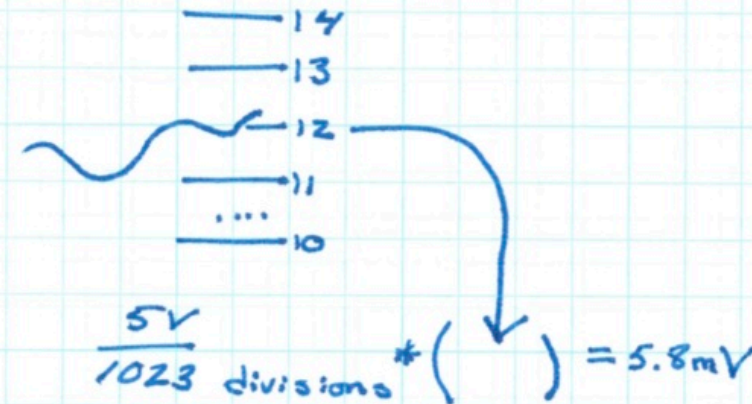
5. (Engineering) Applications

$$\text{Voltage} = a (\text{Temperature}) + b$$

$$\text{Temperature} = \dots$$

From what you already know about Arduinos, please create an algorithm which illustrates the following procedure.

1. The sensor is in contact with an object whose temperature we wish to measure.
2. The sensor outputs a voltage which corresponds to a temperature.
3. The Arduino reads this voltage via an A2D pin.
4. The Arduino converts the integer A2D value into a temperature model (above).
5. The Arduino sends the temperature reading and a time measurement (e.g., your laptop).
6. The Arduino waits a specified time, and then repeats the sequence.



Model Deployment, Applications

Model Development

1. Context-rich Concrete preparation
2. Sensor Data Collection
3. Mathematical Model-Building
4. Algorithmic Model-Building

Model Deployment

5. (Engineering) Applications

1. In the infant incubator, the IR heating lamp should turn on if the sensor reads an infant finger temperature lower than $T_1 = 98.0^\circ F$, and further, the heating lamp should turn off when the temperature exceeds $T_2 = 100.0^\circ F$. Using your model and initial algorithm, create and implement a new algorithm which executes this temperature-control procedure. You can represent the heater's function via an LED, which would be driven by the Arduino. In an actual design, the Arduino would drive a relay, which controls the heater.
2. Children are precious, and it won't do to trust the life of a child to a single \$0.76 component. For greater safety and reliability, consider an improved design which would read in values from two LM34 sensors and actuate a heater if and only if both sensors agree. Create and implement such an algorithm.
3. A rice cooker has two heater settings, the first to get the rice+water up to boiling, and a second heater setting to keep the rice warm once it has fully cooked. Design and implement an algorithm to model the function of a rice-cooker. You can use LED's to represent the function of the two heaters.
4. Whenever you open a refrigerator door, cold air leaks out and the compressor has to run to cool down your food. Create and implement a data collection algorithm that would allow you to capture this data to see how much time it takes to cool the fridge down to proper temperature after the door has been opened.